Computational Data Mining

Part 4: Linear Algebra Linear Systems

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Solving Systems of Linear Equations

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Consider the system of equations

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Two equations and four unknowns, Therefore, in general we would expect infinitely many solutions.

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$$\begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

To capture all other solutions: Generating 0 in a non-trivial way using the columns of the matrix

Solving Systems of Linear Equations

 $\begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \begin{pmatrix} \lambda_1 \begin{bmatrix} 8 \\ 2 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Solving Systems of Linear Equations

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Solving Systems of Linear Equations

$$\begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \begin{pmatrix} \lambda_1 \begin{bmatrix} 8 \\ 2 \\ -1 \\ 0 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \begin{pmatrix} \lambda_2 \begin{bmatrix} -4 \\ 12 \\ 0 \\ -1 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Putting everything together, we obtain the general solution

$$\begin{cases} x \in \mathbb{R}^4 \colon x = \begin{bmatrix} 42\\8\\0\\0 \end{bmatrix} + \lambda_1 \begin{bmatrix} 8\\2\\-1\\0 \end{bmatrix} + \lambda_2 \begin{bmatrix} -4\\12\\0\\-1 \end{bmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R} \end{cases}$$

Solving Systems of Linear Equations

$$\begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \left(\lambda_1 \begin{bmatrix} 8 \\ 2 \\ -1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & 8 & -4 \\ 0 & 1 & 2 & 12 \end{bmatrix} \left(\lambda_2 \begin{bmatrix} -4 \\ 12 \\ 0 \\ -1 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Putting everything together, we obtain the general solution

$$\left\{ x \in \mathbb{R}^4 \colon x = \begin{bmatrix} 42\\8\\0\\0 \end{bmatrix} + \lambda_1 \begin{bmatrix} 8\\2\\-1\\0 \end{bmatrix} + \lambda_2 \begin{bmatrix} -4\\12\\0\\-1 \end{bmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R} \right\}$$

The general approach we followed consisted of the following three steps:

- 1. Find a particular solution to **Ax = b**.
- 2. Find all solutions to **Ax = 0**.
- 3. Combine the solutions to obtain the general solution.

In this way, finding the solutions for a homogeneous equation system **Ax = 0** would be straightforward:



Solving Systems of Linear Equations

In this way, finding the solutions for a homogeneous equation system **Ax = 0** would be straightforward:

$$\boldsymbol{A} = \begin{bmatrix} \mathbf{1} & 3 & 0 & 0 & 3 \\ 0 & 0 & \mathbf{1} & 0 & 9 \\ 0 & 0 & 0 & \mathbf{1} & -4 \end{bmatrix}$$

The key idea for finding the solutions of **Ax = 0** is to look at the **non-pivot columns**

In this way, finding the solutions for a homogeneous equation system **Ax = 0** would be straightforward:

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The key idea for finding the solutions of **Ax = 0** is to look at the **non-pivot columns**

We can express them as a (linear) combination of the pivot columns.

$$\left\{ x \in \mathbb{R}^{5} \colon x = \lambda_{1} \begin{bmatrix} 3 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \lambda_{2} \begin{bmatrix} 3 \\ 0 \\ 9 \\ -4 \\ -1 \end{bmatrix}, \qquad \lambda_{1}, \lambda_{2} \in \mathbb{R} \right\}$$

Solving Systems of Linear Equations

The Minus-1 Trick

A practical trick for reading out the solutions of a homogeneous system of linear equations

Solving Systems of Linear Equations

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	0	· 0	1	*		*	0	*	 *	0	* ···	*	1
	: 7		0	0	•••	0	1	*	 *	1	1	÷	
A =	:	:	:	Ξ		÷	0	:	:	:	:	÷	
	÷	:	÷	:		:	:	÷	÷	0	*	:	
	0	· 0	0	0		0	0	0	 0	1	* •••	*	

We extend this matrix to an n×n-matrix \tilde{A} by adding n – k rows of the form $\begin{bmatrix} 0 & \cdots & 0 & -1 & 0 & \cdots & 0 \end{bmatrix}$

Solving Systems of Linear Equations

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We extend this matrix to an n×n-matrix \tilde{A} by adding n – k rows of the form $\begin{bmatrix} 0 & \cdots & 0 & -1 & 0 & \cdots & 0 \end{bmatrix}$

Then, the columns of \tilde{A} that contain the -1 as pivots are solutions of the homogeneous equation system Ax = 0.

Solving Systems of Linear Equations

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A practical trick for reading out the solutions of a homogeneous system of linear equations

$$\boldsymbol{A} = \begin{bmatrix} \mathbf{1} & 3 & 0 & 0 & 3 \\ 0 & 0 & \mathbf{1} & 0 & 9 \\ 0 & 0 & 0 & \mathbf{1} & -4 \end{bmatrix}$$

Solving Systems of Linear Equations

The Minus-1 Trick

A practical trick for reading out the solutions of a homogeneous system of linear equations $\Gamma 1 = 3 = 0 = 0 = 3$

$$\boldsymbol{A} = \begin{bmatrix} \mathbf{1} & 3 & 0 & 0 & 3 \\ 0 & 0 & \mathbf{1} & 0 & 9 \\ 0 & 0 & 0 & \mathbf{1} & -4 \end{bmatrix} \qquad \tilde{\boldsymbol{A}} = \begin{bmatrix} \mathbf{0} & -\mathbf{1} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ 0 & 0 & 1 & 0 & 9 \\ 0 & 0 & 0 & 1 & -4 \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{1} & -4 \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & -\mathbf{1} \end{bmatrix}$$

Solving Systems of Linear Equations

The Minus-1 Trick

A practical trick for reading out the solutions of a homogeneous system of linear equations $\Gamma = 1$

$$\boldsymbol{A} = \begin{bmatrix} \mathbf{1} & 3 & 0 & 0 & 3 \\ 0 & 0 & \mathbf{1} & 0 & 9 \\ 0 & 0 & 0 & \mathbf{1} & -4 \end{bmatrix} \qquad \tilde{\boldsymbol{A}} = \begin{bmatrix} \mathbf{0} & -\mathbf{1} & 0 & 0 & 0 \\ 0 & -\mathbf{1} & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 9 \\ 0 & 0 & 0 & 1 & -4 \\ 0 & 0 & 0 & 0 & -\mathbf{1} \end{bmatrix}$$

$$\left\{ x \in \mathbb{R}^5 \colon x = \lambda_1 \begin{bmatrix} 3\\ -1\\ 0\\ 0\\ 0\\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 3\\ 0\\ 9\\ -4\\ -1 \end{bmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R} \right\}$$

Checking Linear Independency

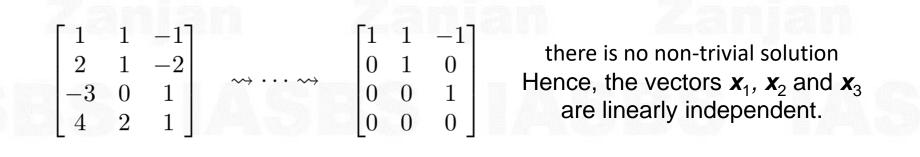
Checking Linear Independency

- All column vectors are linearly independent if and only if all columns are pivot columns.
- If there is at least one non-pivot column, the columns are linearly dependent.

$$\boldsymbol{x}_{1} = \begin{bmatrix} 1\\2\\-3\\4 \end{bmatrix}, \quad \boldsymbol{x}_{2} = \begin{bmatrix} 1\\1\\0\\2 \end{bmatrix}, \quad \boldsymbol{x}_{3} = \begin{bmatrix} -1\\-2\\1\\1\\1 \end{bmatrix} \qquad \lambda_{1} \begin{bmatrix} 1\\2\\-3\\4 \end{bmatrix} + \lambda_{2} \begin{bmatrix} 1\\1\\0\\2 \end{bmatrix} + \lambda_{3} \begin{bmatrix} -1\\-2\\1\\1\\1 \end{bmatrix} = \boldsymbol{0}$$

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$$\boldsymbol{A} = \begin{bmatrix} 1 & -4 & 2 & 17 \\ -2 & -2 & 3 & -10 \\ 1 & 0 & -1 & 11 \\ -1 & 4 & -3 & 1 \end{bmatrix}$$

Checking Linear Independency

A practical way to check the independency is to use Gaussian elimination to solve a homogeneous system of equation:

- All column vectors are linearly independent if and only if all columns are pivot columns.
- If there is at least one non-pivot column, the columns are linearly dependent.

 $\boldsymbol{A} = \begin{bmatrix} 1 & -4 & 2 & 17 \\ -2 & -2 & 3 & -10 \\ 1 & 0 & -1 & 11 \\ -1 & 4 & -3 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & -7 \\ 0 & 1 & 0 & -15 \\ 0 & 0 & 1 & -18 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

This linear equation system is non-trivially solvable! The last column is not a pivot column: $x_4 = -7x_1 - 15x_2 - 18x_3$.

Solving Systems of Linear Equations

Calculating the Inverse

To compute the inverse A^{-1} of $A \in \mathbb{R}^{n \times n}$, we need to find a matrix **X** that satisfies $AX = I_n$.

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use the augmented matrix notation we can write

AX|I $E_1AX|E_1I$ $E_2E_1AX|E_2E_1I$ $E_k...E_2E_1AX|E_k...E_2E_2E_1I$ $IX|E_k...E_2E_2E_1I$

Solving Systems of Linear Equations

Calculating the Inverse

$$A = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

Solving Systems of Linear Equations

Calculating the Inverse

the augmented matrix

	1	0	2	0]	[1	0	2	0	1	0 0 1 0 0 1 0 0	0
A =	1	1	0	0	1	1	0	0	0	1 0	0
	1	2	0	1	1	2	0	1	0	0 1	0
			1		[1	1	1	1	0	0 0	1

Solving Systems of Linear Equations

Calculating the Inverse

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						1	1	0	0	0	1	0	0	
A =	1	2	0	1		1	2	0	1	0	0	1	0	
	1	1	1	1		1	1	1	1	0	0	0	1	

bring it into reduced row-echelon form

$$\begin{bmatrix} 1 & 0 & 0 & 0 & | -1 & 2 & -2 & 2 \\ 0 & 1 & 0 & 0 & | 1 & -1 & 2 & -2 \\ 0 & 0 & 1 & 0 & | 1 & -1 & 1 & -1 \\ 0 & 0 & 0 & 1 & | -1 & 0 & -1 & 2 \end{bmatrix}$$

Solving Systems of Linear Equations

Calculating the Inverse

the augmented matrix

	1	0	2	0]	[1 1 1 1	0	2	0	1	0	0	0]	
A =	1	1	0	0	1	1	0	0	0	1	0	0	
	1	2	0	1	1	2	0	1	0	0	1	0	
			1		[1	1	1	1	0	0	0	1	

bring it into reduced row-echelon form

[1 0	0	0 -1	2	-2	2]			2		
0 1	0	0 1	-1	2	-2	$A^{-1} =$	1	-1	2	-2
0 0	1	0 1	-1	1	-1	A –	1	-1	1	-1
0 0	0	1 –1	0	-1	2		-1	0	-1	2

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- If A is a rectangular matrix:

 $\mathbf{A}\mathbf{x} = \mathbf{b}$ $\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{x} = \mathbf{A}^{\mathsf{T}}\mathbf{b}$

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- If A is a rectangular matrix:

Ax = b $A^{T}Ax = A^{T}b$ $(A^{T}A)^{-1}A^{T}Ax = (A^{T}A)^{-1}A^{T}b$ $x = (A^{T}A)^{-1}A^{T}b$

Moore-Penrose pseudo-inverse



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Example:

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• Calculating all the eigenvalues and just check to see if they're all positive!

A matrix is positive definite if it's symmetric and all its pivots are positive.

Just perform elimination and examine the diagonal terms.

Example: $\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \xrightarrow{\text{elimination}} \begin{bmatrix} 1 & 2 \\ 0 & -3 \end{bmatrix}$

the matrix is not positive definite!

Symmetric, Positive Definite Matrices

A matrix is positive definite $\mathbf{x}^{\mathrm{T}}\mathbf{A}\mathbf{x} > 0$ for any column vector $\mathbf{x} \neq \vec{\mathbf{0}}$





- A matrix is positive definite $\mathbf{x}^{T}\mathbf{A}\mathbf{x} > 0$ for any column vector $\mathbf{x} \neq \vec{0}$ • Example:
- $x^{T}Ax = \begin{bmatrix} x_{1} & x_{2} & x_{3} \end{bmatrix} \begin{vmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{vmatrix} \begin{vmatrix} x_{2} \\ x_{3} \end{vmatrix}$

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 $\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \quad x^{T}Ax = \begin{bmatrix} x_{1} & x_{2} & x_{3} \end{bmatrix} \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix}$ $= (2x_{1}^{2} - 2x_{1}x_{2} + 2x_{2}^{2}) + (x_{3}^{2} - 2x_{2}x_{3})$ $= (x_{1} - x_{2})^{2} + x_{1}^{2} + x_{2}^{2} + (x_{3}^{2} - 2x_{2}x_{3})$ $= (x_{1} - x_{2})^{2} + x_{1}^{2} + (x_{2} - x_{3})^{2} > 0$

A matrix A is positive definite if and only if it can be written as

$\mathbf{A} = \mathbf{R}^{\mathrm{T}}\mathbf{R}, \qquad \begin{bmatrix} 14 & 8 \\ 8 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 1 \\ 3 & 2 \end{bmatrix}$

where \mathbf{R} is a matrix, possibly rectangular, with independent columns.

If the columns of **R** are linearly independent then $\mathbf{R}x \neq 0$ if $x\neq 0$, and so $x^T\mathbf{A}x > 0$.

 $\mathbf{x}^{\mathrm{T}}\mathbf{A}\mathbf{x} = \mathbf{x}^{\mathrm{T}}\mathbf{R}^{\mathrm{T}}\mathbf{R}\mathbf{x} = (\mathbf{R}\mathbf{x})^{\mathrm{T}}(\mathbf{R}\mathbf{x}) = \|\mathbf{R}\mathbf{x}\|^{2}$

