Computational Data Mining

Part 2: Linear Algebra Vectors and Matrices

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Inner product of vectors

er (2-11 km) in (2-21 km)

 $(x, y) = x^T y$





Zanjan

Matrix-Vector Multiplication

ASBS

A: m × n matrix

$$y = Ax,$$
 $y_i = \sum_{j=1}^n a_{ij} x_j,$ $i = 1, ..., m.$

for i=1:m
y(i)=0;
for j=1:n
y(i)=y(i)+A(i,j)*x(j);
end

$$\begin{pmatrix} \times \\ \times \\ \times \\ \times \end{pmatrix} = \begin{pmatrix} \leftarrow & - & - & \rightarrow \\ \leftarrow & - & - & \rightarrow \\ \leftarrow & - & - & \rightarrow \\ \leftarrow & - & - & \rightarrow \end{pmatrix} \begin{pmatrix} \uparrow \\ | \\ | \\ \downarrow \end{pmatrix}$$
end

Matrix-Vector Multiplication

A: m × n matrix
$$y = Ax$$
, $y_i = \sum_{j=1}^n a_{ij}x_j$, $i = 1, \dots, m$







Matrix-Vector Multiplication

A: m × n matrix

$$y = Ax,$$
 $y_i = \sum_{j=1}^{n} a_{ij} x_j,$ $i = 1, ..., m.$





Matrix-Matrix Multiplication

 $\mathbb{R}^{m \times n} \ni C = AB = (c_{ij}),$ $c_{ij} = \sum_{s=1}^{k} a_{is} b_{sj}, \quad i = 1, \dots, m, \quad j = 1, \dots, n.$





Matrix-Matrix Multiplication

```
for i=1:m
  for j=1:n
    for s=1:k
        C(i,j)=C(i,j)+A(i,s)*B(s,j)
        end
    end
end
```





Matrix-Matrix Multiplication

```
for i=1:m
  for j=1:n
    for s=1:k
        C(i,j)=C(i,j)+A(i,s)*B(s,j)
        end
    end
end
```

Inner product version of the code:

```
for i=1:m
  for j=1:n
    C(i,j)=A(i,1:k)*B(1:k,j)
    end
end
```



Matrix-Matrix Multiplication – general form

for ...
for ...
for ...
C(i,j)=C(i,j)+A(i,s)*B(s,j)
end
end
end



Matrix-Matrix product: column-oriented (SAXPY)

for j=1:n
 for s=1:k
 C(1:m,j)=C(1:m,j)+A(1:m,s)*B(s,j)
 end
end





Inner product of vectors

 $(x, y) = x^T y$





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Vector Norms

• The size of a vector

$$\|x\|_{1} = \sum_{i=1}^{n} |x_{i}|, \quad 1\text{-norm},$$
$$\|x\|_{2} = \sqrt{\sum_{i=1}^{n} x_{i}^{2}}, \quad \text{Euclidean norm (2-norm)},$$
$$\|x\|_{\infty} = \max_{1 \le i \le n} |x_{i}|, \quad \text{max-norm.}$$

• General p-norm

$$||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p}$$



Properties of vector norm

• Vector norm is a mapping from $\mathbb{R}^n \rightarrow \mathbb{R}$

$$\begin{split} \| x \| &\geq 0 \text{ for all } x, \\ \| x \| &= 0 \text{ if and only if } x = 0, \\ \| \alpha x \| &= |\alpha| \| x \|, \ \alpha \in \mathbb{R}, \\ \| x + y \| &\leq \| x \| + \| y \|, \text{ the triangle inequality.} \end{split}$$



Use norm for error approximation

- Absolute error

$$\|\delta x\| = \|\bar{x} - x\|$$

Relative error

$$\frac{\|\delta x\|}{\|x\|} = \frac{\|\bar{x} - x\|}{\|x\|}$$



 In a finite dimensional vector space all vector norms are equivalent in the sense that for any two norms || · ||_α and || · ||_β there exist constants m and M such that:

 $m \| x \|_{\alpha} \le \| x \|_{\beta} \le M \| x \|_{\alpha}$

• Example ($x \in R^n$):

 $\|x\|_{2} \le \|x\|_{1} \le \sqrt{n} \|x\|_{2}$





Cosine similarity

• Cosine of the angle between two vectors:

$$\cos \theta(x, y) = \frac{x^T y}{\|x\|_2 \|y\|_2}$$

• What if vectors are orthogonal?





Matrix Norms

• Let ||.|| be a vector norm, the corresponding matrix norm is defined as:

$$||A|| = \sup_{x \neq 0} \frac{||Ax||}{||x||}$$

• Matrix norm satisfies (for $\alpha \in \mathbb{R}$):

$$\begin{split} \|A\| &\geq 0 \text{ for all } A, \\ \|A\| &= 0 \text{ if and only if } A = 0, \\ \|\alpha A\| &= |\alpha| \|A\|, \ \alpha \in \mathbb{R}, \\ \|A + B\| &\leq \|A\| + \|B\|, \text{ the triangle inequality.} \end{split}$$



Proposition 2.1. Let $\|\cdot\|$ denote a vector norm and the corresponding matrix norm. Then

 $||Ax|| \le ||A|| ||x||,$ $||AB|| \le ||A|| ||B||.$









- Matrix 2-norm (matrix as an operator)
 - (square root of largest eigenvalue of A^TA)

$$\|A\|_2 = \left(\max_{1 \le i \le n} \lambda_i(A^T A)\right)^{1/2}$$

m

Matrix 1-norm

$$||A||_1 = \max_{1 \le j \le n} \sum_{i=1}^m |a_{ij}|$$

Matrix inf-norm

$$||A||_{\infty} = \max_{1 \le i \le m} \sum_{j=1}^{n} |a_{ij}|$$



- Frobenius matrix norm
 - matrix as a point of space of dimension mn

$$||A||_F = \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} a_{ij}^2}$$

$$\|A\|_F^2 = \operatorname{tr}(A^T A)$$

• Trace of matrix B = sum of diagonal elements

$$\operatorname{tr}(B) = \sum_{i=1}^{n} b_{ii}$$



Linear Independence: Bases

Given a set of vectors $(v_j)_{j=1}^n$ in \mathbb{R}^m , $m \ge n$, $\operatorname{span}(v_1, v_2, \dots, v_n) = \left\{ y \mid y = \sum_{j=1}^n \alpha_j v_j \right\}$

The vectors $(v_j)_{j=1}^n$ are called *linearly independent*

 $\sum_{j=1}^{n} \alpha_j v_j = 0$ if and only if $\alpha_j = 0$ for $j = 1, 2, \ldots, n$.



Proposition 2.2. Assume that the vectors $(v_j)_{j=1}^n$ are linearly dependent.

Then some v_k can be written as linear combinations of the rest,

$$v_k = \sum_{j \neq k} \beta_j v_j$$



Rank of Matrix

Maximum number of linearly independent column vectors











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 Proposition 2.3. An outer product matrix xy^T, where x and y are vectors in Rⁿ, has rank 1.

$$xy^{T} = \begin{pmatrix} y_{1}x & y_{2}x & \cdots & y_{n}x \end{pmatrix} = \begin{pmatrix} x_{1}y^{T} \\ x_{2}y^{T} \\ \vdots \\ x_{n}y^{T} \end{pmatrix}$$







Nonsingular matrix

- A square matrix $A \in \mathbb{R}^{n \times n}$ with rank n
- Has an inverse A^{-1} satisfying

$$A^{-1}A = AA^{-1} = \mathbf{I}$$

If we multiply **linearly independent vectors** by a **nonsingular matrix**, then the vectors remain linearly independent.



Proposition 2.4. Assume that the vectors v_1, \ldots, v_p are linearly independent. Then for any nonsingular matrix T, the vectors Tv_1, \ldots, Tv_p are linearly independent.

Proof. Obviously $\sum_{j=1}^{p} \alpha_j v_j = 0$ if and only if $\sum_{j=1}^{p} \alpha_j T v_j = 0$ (since we can multiply any of the equations by T or T^{-1}). Therefore the statement follows. \Box



Weather prediction example

		today		
		sunny	cloudy	rainy
tomorrow	sunny	0.4	0.3	0.1
	cloudy	0.4	0.3	0.6
	rainy	0.2	0.4	0.3

If today is cloudy, what is the probability that tomorrow is:

- Cloudy?
- Sunny?
- Rainy?



Weather prediction example

		today		
		sunny	cloudy	rainy
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	cloudy	0.4	0.3	0.6
	rainy	0.2	0.4	0.3

If today is cloudy, what is the probability that tomorrow is:

- Cloudy? 0.3
- Sunny? 0.3
- Rainy? 0.4



Weather prediction example

		today		
		sunny	cloudy	rainy
tomorrow	sunny	0.4	0.3	0.1
	cloudy	0.4	0.3	0.6
	rainy	0.2	0.4	0.3

If today is cloudy, what is the probability that the day after tomorrow is:

- Cloudy?
- Sunny?
- Rainy?



Any Question?

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